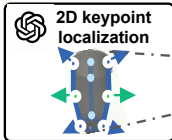


Observations

Promptable 3D Perception



3D Lifting (LFM)



Planner

Send Program

Get Contract

Grounded Contract

Cartesian Waypoints



AgenSkillGraph

Geometric Contracts



Required Primitives:

k_1 : left_side_mid

k_2 : right_side_mid

Constraints $\mathcal{N}$: horizontal

Grasp Cup



Move to Box



Rotate Cup



Stack Cone



Place Lego



Grasp semantic parts

Grasp head of the penguin



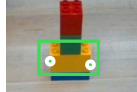
Pour Cup



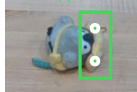
Fold Towel



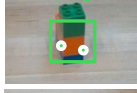
Grasp yellow brick



Grasp yellow hat



Grasp orange brick



Pick Cable



Press Button



Grasp the green plastic



Unscrew Button



Pick Pen

